

POLYNOMIAL APPROXIMATIONS OF REGULAR AND SINGULAR VECTOR FIELDS WITH APPLICATIONS TO PROBLEMS OF ELECTROMAGNETICS

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Outline of the talk

1. Problem formulation.
2. $\mathbf{H}(\text{div})$ -conforming p -interpolation in two dimensions:
 - classical Raviart-Thomas interpolation operators;
 - projection based interpolation operators;
 - error estimation.
3. Application: hp -BEM for 3D problem of electromagnetic scattering:
 - convergence and error analysis;
 - approximation of singularities.
4. Conclusions.
5. References.

Polynomial approximations of vector fields: problem formulation

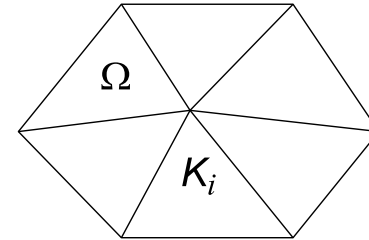
Notation

$\Omega \subset \mathbb{R}^2$ – a polygonal domain; $\bar{\Omega} = \cup_i \bar{K}_i^h$;

$h > 0$ – mesh parameter; $p \geq 1$ – polynomial degree;

$\mathbf{u}(\mathbf{x}) = (u_1(\mathbf{x}), u_2(\mathbf{x}))$, $\mathbf{x} = (x_1, x_2) \in \Omega$;

$\mathbf{H}^r(\text{div}, \Omega) := \{\mathbf{u} \in \mathbf{H}^r(\Omega); \text{div } \mathbf{u} \in H^r(\Omega)\}$, $r \geq 0$.



Polynomial approximations of vector fields: problem formulation

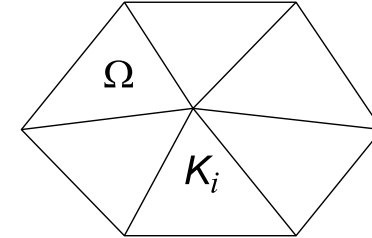
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The problem

Given $\mathbf{u} \in \mathbf{H}^r(\text{div}, \Omega)$ with $r > 0$, find $\mathbf{v}(\mathbf{x}) = (v_1(\mathbf{x}), v_2(\mathbf{x}))$ such that

- $v_1(\mathbf{x}), v_2(\mathbf{x})$ are piecewise polynomials of degree p ,
- $\mathbf{v} \in \mathbf{H}(\text{div}, \Omega) = \{\mathbf{v} \in \mathbf{L}^2(\Omega); \text{div } \mathbf{v} \in L^2(\Omega)\}$,
- $\mathbf{u}(\mathbf{x}) \approx \mathbf{v}(\mathbf{x})$, i.e., $\|\mathbf{u} - \mathbf{v}\|_{\mathbf{H}(\text{div}, \Omega)} \rightarrow 0$ as $h \rightarrow 0$ and/or $p \rightarrow \infty$.

Polynomial approximations of vector fields: problem formulation

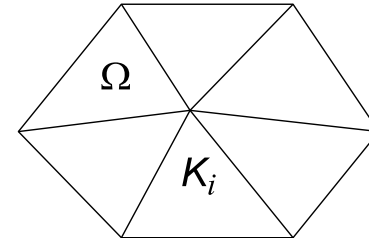
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Applications

- * Mixed finite element methods for elliptic problems
- * FEM for Maxwell's equations in 2D (due to isomorphism of div and curl)
- * $\mathbf{H}(\text{div})$ -conforming BEM for Maxwell's equations in 3D

Polynomial approximations of vector fields: problem formulation

[Raviart, Thomas '77], [Brezzi, Fortin '91]

Reference element K : equilateral triangle T or unit square Q .

Polynomial space on K : the Raviart-Thomas space of order $p \geq 1$,

$$\mathbf{P}_p^{\text{RT}}(K) = \begin{cases} (\mathcal{P}_{p-1}(T))^2 \oplus \mathbf{x} \mathcal{P}_{p-1}(T) & \text{if } K = T, \\ \mathcal{P}_{p,p-1}(Q) \times \mathcal{P}_{p-1,p}(Q) & \text{if } K = Q. \end{cases}$$

The problem

Given $\mathbf{u} \in \mathbf{H}^r(\text{div}, K)$ with $r > 0$, find $\mathbf{u}_p \in \mathbf{P}_p^{\text{RT}}(K)$ and $\delta_p(r)$ such that

- i) \mathbf{u}_p is well-defined and stable (with respect to p) for any $r > 0$;
- ii) \mathbf{u}_p allows to construct $\mathbf{H}(\text{div})$ -conforming approximations on a patch of elements (e.g., \mathbf{u}_p interpolates normal components of \mathbf{u} along ∂K);
- iii) $\|\mathbf{u} - \mathbf{u}_p\|_{\mathbf{H}(\text{div}, K)} \preceq \delta_p(r) \|\mathbf{u}\|_{\mathbf{H}^r(\text{div}, K)}$ and $\delta_p(r) \rightarrow 0$ as $p \rightarrow \infty$.

Classical $\mathbf{H}(\text{div})$ -conforming interpolation operator Π_p^{RT}

[Raviart, Thomas '77], [Brezzi, Fortin '91]

$\forall \mathbf{u} \in \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K)$ the interpolant $\Pi_p^{\text{RT}} \mathbf{u}$ is defined by the conditions

$$\langle \mathbf{u} - \Pi_p^{\text{RT}} \mathbf{u}, \mathbf{v} \rangle_{0,K} = 0 \quad \forall \mathbf{v} \in \begin{cases} (\mathcal{P}_{p-2}(T))^2 & \text{if } K = T, \\ \mathcal{P}_{p-2,p-1}(Q) \times \mathcal{P}_{p-1,p-2}(Q) & \text{if } K = Q; \end{cases}$$

$$\langle (\mathbf{u} - \Pi_p^{\text{RT}} \mathbf{u}) \cdot \mathbf{n}, w \rangle_{0,\ell} = 0 \quad \forall w \in \mathcal{P}_{p-1}(\ell) \text{ and } \forall \ell \subset \partial K.$$

Commuting diagram property:

$$\begin{array}{ccc} \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K) & \xrightarrow{\text{div}} & L^2(K) \\ \downarrow \Pi_p^{\text{RT}} & & \downarrow \Pi_{p-1}^0 \\ \mathbf{P}_p^{\text{RT}}(K) & \xrightarrow{\text{div}} & \mathcal{P}_{p-1}(K), \end{array}$$

where $\Pi_p^0: L^2(K) \rightarrow \mathcal{P}_p(K)$ denotes the standard L^2 -projection onto $\mathcal{P}_p(K)$.

Classical $\mathbf{H}(\text{div})$ -conforming interpolation operator Π_p^{RT}

Error estimation for p -interpolation on the square Q

[Suri '90], [Milner, Suri '92], [Stenberg, Suri '97], [Ainsworth, Pinchedez '02]

$$\|\mathbf{u} - \Pi_p^{\text{RT}} \mathbf{u}\|_{\mathbf{H}(\text{div}, Q)} \preceq p^{-(r-1/2-\varepsilon)} \|\mathbf{u}\|_{\mathbf{H}^r(\text{div}, Q)}, \quad r > 1/2.$$

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In 3D: $\mathbf{H}(\text{curl})$ -conforming Nédélec's elements *on the cube*

[Monk '94], [Ben Belgacem, Bernardi '99]

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Conclusions:

- lack of stability (with respect to p) for low-regular fields;
- optimal p -estimates can hardly be achieved;
- it is not clear how to deal with triangular elements.

Projection-based $\mathbf{H}(\text{div})$ -conforming interpolation operator Π_p^{div}

[Demkowicz, Babuška '03]

$\forall \mathbf{u} \in \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K)$ with $r > 0$, the interpolant $\Pi_p^{\text{div}} \mathbf{u}$ is defined as

$$\Pi_p^{\text{div}} \mathbf{u} = \mathbf{u}_1 + \mathbf{u}_2^p + \mathbf{u}_3^p \in \mathbf{P}_p^{\text{RT}}(K),$$

where

$\mathbf{u}_1 = \sum_{\ell \subset \partial K} \left(\int_{\ell} \mathbf{u} \cdot \mathbf{n} \right) \phi_{\ell}$ – the lowest order interpolant ($\phi_{\ell} \in \mathbf{P}_1^{\text{RT}}(K)$),

\mathbf{u}_2^p – the sum of edge interpolants,

\mathbf{u}_3^p – an interior interpolant (vector bubble function) satisfying

$$\langle \text{div}(\mathbf{u} - (\mathbf{u}_1 + \mathbf{u}_2^p + \mathbf{u}_3^p)), \text{div} \mathbf{v} \rangle_{0,K} = 0 \quad \forall \mathbf{v} \in \mathbf{P}_p^{\text{RT},0}(K),$$

$$\langle \mathbf{u} - (\mathbf{u}_1 + \mathbf{u}_2^p + \mathbf{u}_3^p), \mathbf{curl} \phi \rangle_{0,K} = 0 \quad \forall \phi \in \mathcal{P}_p^0(K).$$

Projection-based $\mathbf{H}(\text{div})$ -conforming interpolation operator Π_p^{div}

[Demkowicz, Babuška '03]

$$\forall \mathbf{u} \in \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K), r > 0: \Pi_p^{\text{div}} \mathbf{u} = \mathbf{u}_1 + \mathbf{u}_2^p + \mathbf{u}_3^p \in \mathbf{P}_p^{\text{RT}}(K).$$

Properties of the operator Π_p^{div} :

- Π_p^{div} is well defined and stable (w.r.t. p) for any $r > 0$;
- it preserves polynomial vector fields from $\mathbf{P}_p^{\text{RT}}(K)$;
- it works equally well on both triangles and parallelograms;
- it can be easily generalised to allow variation of polynomial degrees;
- it makes de Rham diagram commute

$$\begin{array}{ccccccc} H^{1+r}(K) & \xrightarrow{\text{curl}} & \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K) & \xrightarrow{\text{div}} & L^2(K) \\ \downarrow \Pi_p^1 & & \downarrow \Pi_p^{\text{div}} & & \downarrow \Pi_{p-1}^0 \\ \mathcal{P}_p(K) & \xrightarrow{\text{curl}} & \mathbf{P}_p^{\text{RT}}(K) & \xrightarrow{\text{div}} & \mathcal{P}_{p-1}(K), \end{array}$$

where $\Pi_p^1 : H^{1+r}(K) \rightarrow \mathcal{P}_p(K)$ is the H^1 -conforming interpolation operator.

Projection-based $\mathbf{H}(\text{div})$ -conforming interpolation operator Π_p^{div}

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Interpolation error estimation

If $\mathbf{u} \in \mathbf{H}^r(\text{div}, K)$ with $0 < r < 1$, then there holds

$$\|\mathbf{u} - \Pi_p^{\text{div}} \mathbf{u}\|_{\mathbf{H}(\text{div}, K)} \leq C(\varepsilon) p^{-(r-\varepsilon)} \|\mathbf{u}\|_{\mathbf{H}^r(\text{div}, K)}, \quad 0 < \varepsilon < r.$$

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Orthogonal (Helmholtz) decomposition of $\mathbf{u} \in \mathbf{H}^r(\text{div}, K)$:

$$\mathbf{u} = \mathbf{u}_0 + \mathbf{curl} \psi, \quad \langle \mathbf{u}_0, \mathbf{curl} \phi \rangle_{0,K} = 0 \quad \forall \phi \in H^1(K).$$

Hence, one has limited regularity of \mathbf{u}_0 and ψ !

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$$\forall \mathbf{u} \in \mathbf{H}^r(K) \cap \mathbf{H}(\text{div}, K), r > 0: \Pi_p^{\text{div}} \mathbf{u} = \mathbf{u}_1 + \mathbf{u}_2^p + \mathbf{u}_3^p \in \mathbf{P}_p^{\text{RT}}(K).$$

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Conclusions on the interpolation error estimation:

- Π_p^{div} satisfies a sub-optimal interpolation error estimate;
- error estimate is available only for fields with limited regularity.

Regular decompositions via Poincaré-type integral operators

The Poincaré map $R_{\mathbf{a}} : C^\infty(\bar{K}) \rightarrow (C^\infty(\bar{K}))^2$ for some $\mathbf{a} = (a_1, a_2) \in \bar{K}$:

$$R_{\mathbf{a}}\psi = (R_1, R_2), \quad R_i(\mathbf{x}) := (x_i - a_i) \int_0^1 t\psi(\mathbf{a} + t(\mathbf{x} - \mathbf{a})) dt, \quad i = 1, 2.$$

Properties:

- $\operatorname{div}(R_{\mathbf{a}}\psi) = \psi \quad \forall \psi \in C^1(\bar{K})$;
- $R_{\mathbf{a}}$ maps $\mathcal{P}_p(K)$ into $\mathbf{P}_{p+1}^{\text{RT}}(K)$;
- $R_{\mathbf{a}}$ cannot be extended to a continuous mapping $L^2(K) \rightarrow \mathbf{H}^1(K)$.

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[Costabel, McIntosh '10]: the regularised Poincaré operator

$$R : C^\infty(\bar{K}) \rightarrow (C^\infty(\bar{K}))^2, \quad R\psi := \int_B \theta(\mathbf{a}) R_{\mathbf{a}}\psi d\mathbf{a},$$

where $\theta \in C^\infty(\mathbb{R}^2)$, $\text{supp } \theta \subset B \subset K$, $\int_B \theta(\mathbf{a}) d\mathbf{a} = 1$, $\mathbf{a} = (a_1, a_2)$.

Properties:

- $\text{div}(R\psi) = \psi \quad \forall \psi \in H^r(K), \quad r \geq 0$;
- R maps $\mathcal{P}_p(K)$ into $\mathbf{P}_{p+1}^{\text{RT}}(K)$;
- R defines a bounded operator $H^{r-1}(K) \rightarrow \mathbf{H}^r(K)$ for any $r \geq 0$.

Regular decompositions via Poincaré-type integral operators

[Costabel, McIntosh '10]: regularised Poincaré integral operators

$$R : H^{r-1}(K) \hookrightarrow \mathbf{H}^r(K), \quad r \geq 0, \quad \operatorname{div}(R\psi) = \psi \quad \forall \psi \in H^r(K);$$

$$A : \mathbf{H}^r(K) \hookrightarrow H^{r+1}(K), \quad r \geq 0, \quad \mathbf{curl}(A\mathbf{u}) = \mathbf{u} \quad \forall \mathbf{u} \in \mathbf{H}^r(\operatorname{div}0, K).$$

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Lemma 1. Let $\mathbf{u} \in \mathbf{H}^r(\operatorname{div}, K)$, $r > 0$. Then there exist $\psi \in H^{r+1}(K)$ and $\mathbf{v} \in \mathbf{H}^{r+1}(K)$ such that $\mathbf{u} = \mathbf{curl} \psi + \mathbf{v}$. Moreover,

$$\|\mathbf{v}\|_{\mathbf{H}^{r+1}(K)} \preceq \|\operatorname{div} \mathbf{u}\|_{H^r(K)} \quad \text{and} \quad \|\psi\|_{H^{r+1}(K)} \preceq \|\mathbf{u}\|_{\mathbf{H}^r(K)}. \quad (1)$$

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Proof. 1) $\operatorname{div} \mathbf{u} \in H^r(K) \Rightarrow \mathbf{v} := R(\operatorname{div} \mathbf{u}) \in \mathbf{H}^{r+1}(K)$ and

$$\mathbf{u} = (\mathbf{u} - R(\operatorname{div} \mathbf{u})) + R(\operatorname{div} \mathbf{u}) = (\mathbf{u} - R(\operatorname{div} \mathbf{u})) + \mathbf{v}.$$

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2) $\mathbf{u} - R(\operatorname{div} \mathbf{u}) \in \mathbf{H}^r(K)$, $\operatorname{div}(\mathbf{u} - R(\operatorname{div} \mathbf{u})) = \operatorname{div} \mathbf{u} - \operatorname{div}(R(\operatorname{div} \mathbf{u})) = 0$.

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2) $\mathbf{u} - R(\operatorname{div} \mathbf{u}) \in \mathbf{H}^r(K)$, $\operatorname{div}(\mathbf{u} - R(\operatorname{div} \mathbf{u})) = \operatorname{div} \mathbf{u} - \operatorname{div}(R(\operatorname{div} \mathbf{u})) = 0$.

3) $\psi := A(\mathbf{u} - R(\operatorname{div} \mathbf{u})) \in H^{r+1}(K)$ and $\mathbf{curl} \psi = \mathbf{u} - R(\operatorname{div} \mathbf{u})$. \square

Optimal error estimation for $\mathbf{H}(\text{div})$ -conforming p -interpolation

Theorem 1. Let $\mathbf{u} \in \mathbf{H}^r(\text{div}, K)$, $r > 0$. Then there holds

$$\|\mathbf{u} - \Pi_p^{\text{div}} \mathbf{u}\|_{\mathbf{H}(\text{div}, K)} \preceq p^{-r} \|\mathbf{u}\|_{\mathbf{H}^r(\text{div}, K)}.$$

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Proof. 1) Lemma 1: $\mathbf{u} = \mathbf{curl} \psi + \mathbf{v}$, $\psi \in H^{r+1}(K)$, $\mathbf{v} \in \mathbf{H}^{r+1}(K)$.

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Proof. 1) Lemma 1: $\mathbf{u} = \mathbf{curl} \psi + \mathbf{v}$, $\psi \in H^{r+1}(K)$, $\mathbf{v} \in \mathbf{H}^{r+1}(K)$.

$$2) \Pi_p^{\text{div}} \mathbf{u} = \Pi_p^{\text{div}}(\mathbf{curl} \psi) + \Pi_p^{\text{div}} \mathbf{v} = \mathbf{curl}(\Pi_p^1 \psi) + \Pi_p^{\text{div}} \mathbf{v}.$$

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Proof. 1) Lemma 1: $\mathbf{u} = \mathbf{curl} \psi + \mathbf{v}$, $\psi \in H^{r+1}(K)$, $\mathbf{v} \in \mathbf{H}^{r+1}(K)$.

$$2) \Pi_p^{\text{div}} \mathbf{u} = \Pi_p^{\text{div}}(\mathbf{curl} \psi) + \Pi_p^{\text{div}} \mathbf{v} = \mathbf{curl}(\Pi_p^1 \psi) + \Pi_p^{\text{div}} \mathbf{v}.$$

$$3) \mathbf{u} - \Pi_p^{\text{div}} \mathbf{u} = \mathbf{curl}(\psi - \Pi_p^1 \psi) + (\mathbf{v} - \Pi_p^{\text{div}} \mathbf{v}).$$

Optimal error estimation for $\mathbf{H}(\text{div})$ -conforming p -interpolation

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$$5) \|\mathbf{v} - \Pi_p^{\text{div}} \mathbf{v}\|_{\mathbf{H}(\text{div}, K)} \\ \leq \inf_{\mathbf{v}_p} \left(\|\mathbf{v} - \mathbf{v}_p\|_{\mathbf{H}(\text{div}, K)} + \|\Pi_p^{\text{div}}(\mathbf{v} - \mathbf{v}_p)\|_{\mathbf{H}(\text{div}, K)} \right) \\ \stackrel{\varepsilon \in (0,1)}{\preceq} \inf_{\mathbf{v}_p} \left(\|\mathbf{v} - \mathbf{v}_p\|_{\mathbf{H}^\varepsilon(K)} + \|\text{div}(\mathbf{v} - \mathbf{v}_p)\|_{L^2(K)} \right) \preceq \inf_{\mathbf{v}_p} \|\mathbf{v} - \mathbf{v}_p\|_{\mathbf{H}^1(K)}.$$

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6) Combine 4) and 5), then use 3). □

Optimal error estimation for $\mathbf{H}(\text{div})$ -conforming p -interpolation

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Immediate (and important) extensions and applications

- * Brezzi-Douglas-Marini space on the reference **triangle**
- * Optimal hp -estimates (by the Bramble-Hilbert argument and scaling)

$$\|\mathbf{u} - \Pi_{hp}^{\text{div}} \mathbf{u}\|_{\mathbf{H}(\text{div}, \Omega)} \preceq h^{\min\{r,p\}} p^{-r} \|\mathbf{u}\|_{\mathbf{H}^r(\text{div}, \Omega)}$$

- * $\mathbf{H}(\text{curl})$ -conforming p -interpolation operator in 2D (due to isomorphism of div and curl). Application: p - and hp -FEM for Maxwell's equations in 2D.

Application: *hp*-BEM for 3D problem of electromagnetic scattering

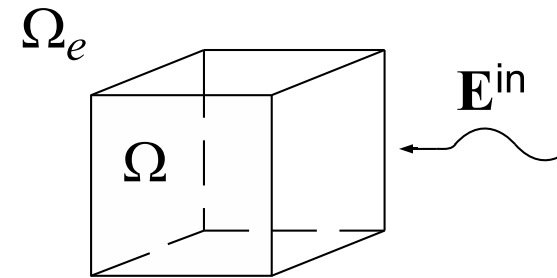
Boundary value problem for PDE (3D problem of e/m scattering)

Assumptions:

Ω is a perfectly conducting body in \mathbb{R}^3 ,

$\Gamma = \partial\Omega$ is a Lipschitz polyhedral surface.

$\Omega_e := \mathbb{R}^3 \setminus \bar{\Omega}$.



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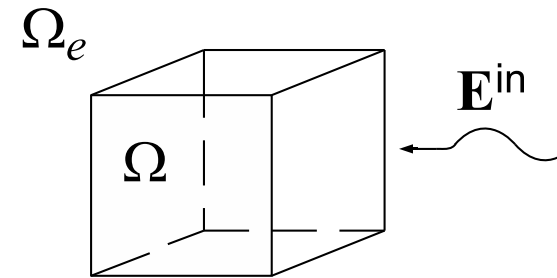
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Time-harmonic Maxwell's equations in Ω_e :

$$\begin{cases} \mathbf{curl} \mathbf{E} - i\omega \mu \mathbf{H} = \mathbf{0} \\ \mathbf{curl} \mathbf{H} + i\omega \varepsilon \mathbf{E} = \mathbf{0} \end{cases} \quad \text{or} \quad \begin{cases} \mathbf{curl} \mathbf{curl} \mathbf{E} - k^2 \mathbf{E} = \mathbf{0}, \\ k := \omega \sqrt{\mu \varepsilon}, \mathbf{H} = (i\omega \mu)^{-1} \mathbf{curl} \mathbf{E}. \end{cases}$$

Boundary condition on Γ : $\gamma_{\tau}(\mathbf{E}) = -\gamma_{\tau}(\mathbf{E}^{\text{in}})$,

where \mathbf{E}^{in} is some incident plane wave with wave number k , $\gamma_{\tau} : \mathbf{u} \mapsto \mathbf{u} \times \boldsymbol{\nu}|_{\Gamma}$.

Silver-Müller radiation condition at ∞ .

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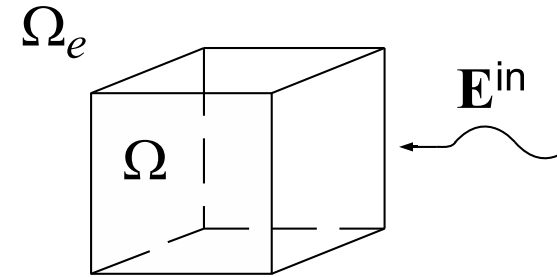
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$$\mathbf{E}, \mathbf{H} \in \mathbf{H}_{\text{loc}}(\mathbf{curl}, \Omega_e) := \{\mathbf{u} \in \mathbf{L}_{\text{loc}}^2(\Omega_e); \mathbf{curl} \mathbf{u} \in \mathbf{L}_{\text{loc}}^2(\Omega_e)\}.$$

Application: *hp*-BEM for 3D problem of electromagnetic scattering

Boundary integral equation: weak formulation, unique solvability, regularity

\mathbf{u} – jump of the magnetic field \mathbf{H} at the interface Γ ;

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The BIE: the electric field integral equation (EFIE) for \mathbf{u} .

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The BIE: the electric field integral equation (EFIE) for \mathbf{u} .

Variational form of the EFIE (Rumsey's principle): find $\mathbf{u} \in \mathbf{X}$ such that

$$a(\mathbf{u}, \mathbf{v}) := \langle \gamma_{\text{tr}}(V_k \text{div}_\Gamma \mathbf{u}), \text{div}_\Gamma \mathbf{v} \rangle - k^2 \langle \pi_\tau(\mathbf{V}_k \mathbf{u}), \mathbf{v} \rangle = \langle \mathbf{f}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{X},$$

where $\pi_\tau: \mathbf{u} \mapsto \boldsymbol{\nu} \times (\mathbf{u} \times \boldsymbol{\nu})|_\Gamma$, $\mathbf{f} := \pi_\tau(\mathbf{E}^{\text{in}})$, and V_k, \mathbf{V}_k are single layer operators for given k .

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Remark.

The form $a(\mathbf{u}, \mathbf{v})$ is not \mathbf{X} -coercive due to infinite-dimensional kernel of div_Γ .

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[Buffa, Costabel, Schwab '02], [Hiptmair, Schwab '02]:

if k^2 is not an electrical eigenvalue of the interior problem, then there exists a unique $\mathbf{u} \in \mathbf{X}$.

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[Costabel, Dauge '00] $\Rightarrow \exists s \in (0, \frac{1}{2})$ such that $\mathbf{u} \in \mathbf{H}^s(\text{div}_\Gamma, \Gamma)$.

Application: hp -BEM for 3D problem of electromagnetic scattering

Galerkin BEM: discrete formulation, unique solvability, quasi-optimality

Surface discretisation: a family of quasi-uniform meshes $\Delta_h = \{\Gamma_j\}$ on Γ .

Discrete subspace: $\mathbf{X}_N \subset \mathbf{H}(\operatorname{div}_\Gamma, \Gamma) \subset \mathbf{X}$ is based on Raviart-Thomas spaces.

$\mathbf{P}_p^{\text{RT}}(K) = (\mathcal{P}_{p-1}(K))^2 \oplus \boldsymbol{\xi} \mathcal{P}_{p-1}(K)$, K is the ref. element.

$N = N(h, p)$, $h > 0$ is the mesh parameter, $p \geq 1$ is a polynomial degree.

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Galerkin BEM: find $\mathbf{u}_N \in \mathbf{X}_N$ such that $a(\mathbf{u}_N, \mathbf{v}) = \langle \mathbf{f}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{X}_N$.

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Theorem 2 [B., Heuer, Hiptmair '10].

For $N = N(h, p)$ large enough, the discrete problem is uniquely solvable, and the hp -BEM converges quasi-optimally, i.e.,

$$\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} \preceq \inf\{\|\mathbf{u} - \mathbf{v}\|_{\mathbf{X}}; \mathbf{v} \in \mathbf{X}_N\}.$$

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Main ingredients in the proof:

- decompositions $\mathbf{X} = \mathbf{V} \oplus \mathbf{W}$, $\mathbf{V} \subset \mathbf{H}_{\perp}^{1/2}(\Gamma)$, $\mathbf{W} = \mathbf{H}^{-1/2}(\operatorname{div}_{\Gamma} 0, \Gamma)$
and $\mathbf{X}_N = \mathbf{V}_N \oplus \mathbf{W}_N$, $\mathbf{W}_N \subset \mathbf{W}$;
- projection based interpolation operators [Demkowicz, Babuška '03];
- the regularised Poincaré integral operators [Costabel, McIntosh '10].

Application: hp -BEM for 3D problem of electromagnetic scattering

A priori error estimation (based on the Sobolev regularity)

Theorem 3 [B., Heuer '10].

There exists $s > 0$ such that $\mathbf{u} \in \mathbf{H}_-^s(\operatorname{div}_\Gamma, \Gamma)$ and

$$\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} \preceq h^{1/2 + \min\{s, p\}} p^{-(s+1/2)} \|\mathbf{u}\|_{\mathbf{H}_-^s(\operatorname{div}_\Gamma, \Gamma)}.$$

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Proof: use $\mathbf{H}(\operatorname{div}_\Gamma, \Gamma)$ -conforming projection-based interpolation operator

$\Pi_{hp}^{\operatorname{div}} : \mathbf{H}_-^s(\operatorname{div}_\Gamma, \Gamma) \rightarrow \mathbf{X}_N$ and recall that $\mathbf{X} = \mathbf{H}^{-1/2}(\operatorname{div}_\Gamma, \Gamma)$.

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Careful here: $\mathbf{X} = \mathbf{H}^{-1/2}(\operatorname{div}_\Gamma, \Gamma)$ is not the dual space of $\mathbf{H}^{1/2}(\operatorname{div}_\Gamma, \Gamma)$ with respect to the $\mathbf{H}(\operatorname{div}_\Gamma, \Gamma)$ -inner product (unless Γ is smooth)! Use duality face by face. Localisation of $\mathbf{H}^{-1/2}(\operatorname{div}_\Gamma, \Gamma)$ to faces is not trivial.

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$\Pi_{hp}^{\operatorname{div}} : \mathbf{H}_-^s(\operatorname{div}_\Gamma, \Gamma) \rightarrow \mathbf{X}_N$ and recall that $\mathbf{X} = \mathbf{H}^{-1/2}(\operatorname{div}_\Gamma, \Gamma)$.

$$\text{Step 1: } \|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} \preceq \|\mathbf{u} - \Pi_{hp}^{\operatorname{div}} \mathbf{u}\|_{\mathbf{X}} \preceq h^{1/2} p^{-1/2} \|\mathbf{u} - \Pi_{hp}^{\operatorname{div}} \mathbf{u}\|_{\mathbf{H}(\operatorname{div}_\Gamma, \Gamma)}.$$

$$\text{Step 2: } \|\mathbf{u} - \Pi_{hp}^{\operatorname{div}} \mathbf{u}\|_{\mathbf{H}(\operatorname{div}_\Gamma, \Gamma)} \preceq h^{\min\{s, p\}} p^{-s} \|\mathbf{u}\|_{\mathbf{H}_-^s(\operatorname{div}_\Gamma, \Gamma)}, \quad s > 0. \quad \square$$

Application: hp -BEM for 3D problem of electromagnetic scattering

A priori error estimation (based on the Sobolev regularity)

Theorem 3 [B., Heuer '10].

There exists $s > 0$ such that $\mathbf{u} \in \mathbf{H}^s(\operatorname{div}_\Gamma, \Gamma)$ and

$$\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} \preceq h^{1/2 + \min\{s, p\}} p^{-(s+1/2)} \|\mathbf{u}\|_{\mathbf{H}^s(\operatorname{div}_\Gamma, \Gamma)}.$$

Convergence rates

For the exterior problem $\mathbf{u} \in \mathbf{H}^s(\operatorname{div}_\Gamma, \Gamma)$ with $s \in (0, \frac{1}{2})$.

h -version: $p \geq 1$ is fixed, $N \simeq h^{-2}$, $\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} = \mathcal{O}(N^{-1/2(s+1/2)})$.

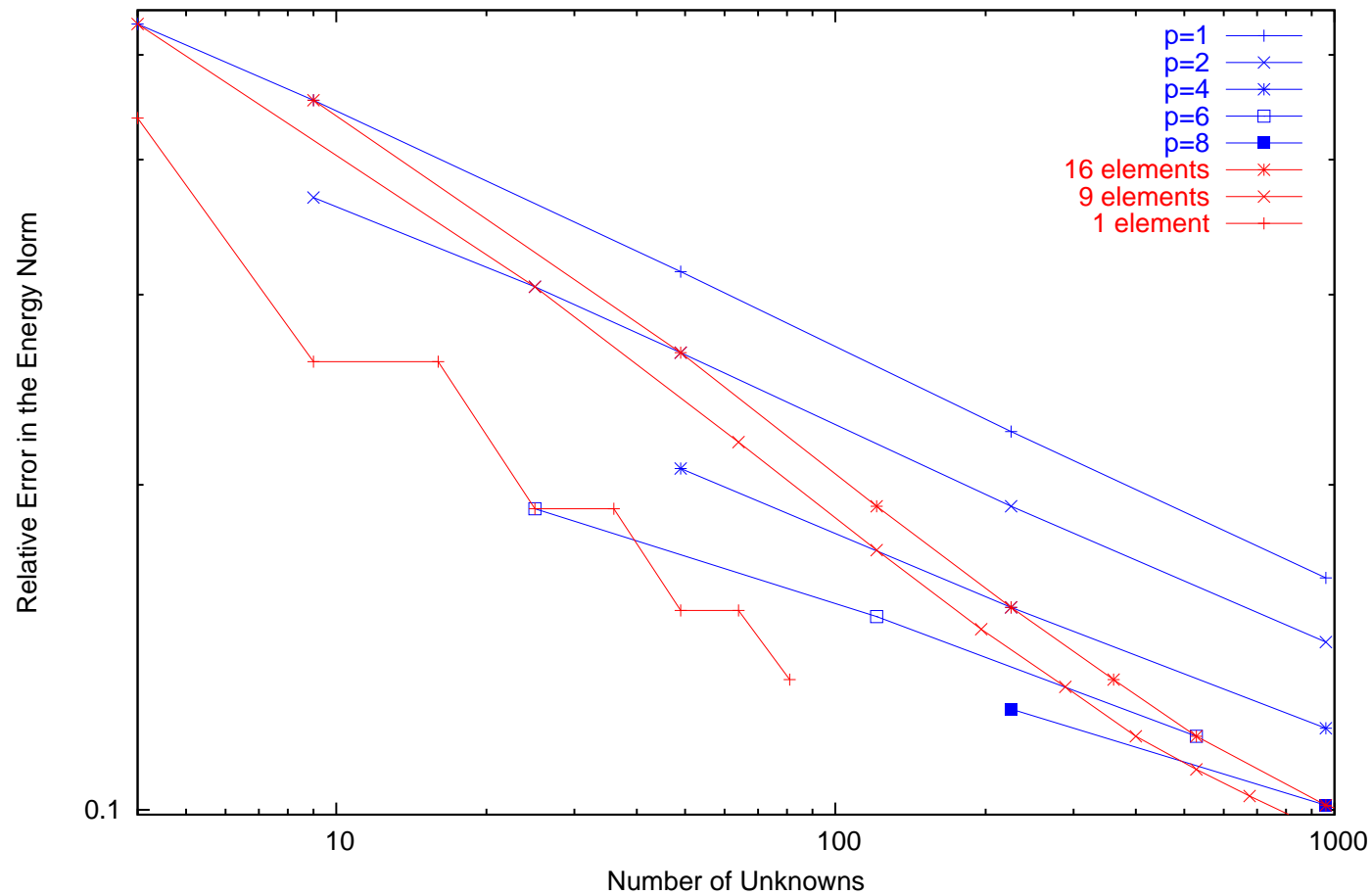
p -version: h is fixed, $N \simeq p^2$, $\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} = \mathcal{O}(N^{-1/2(s+1/2)})$.

Available numerical results

[Leydecker; PhD Thesis '06]: the p -BEM converges faster than the h -BEM.

Application: hp -BEM for 3D problem of electromagnetic scattering

Available numerical results



Application: hp -BEM for 3D problem of electromagnetic scattering

Precise a priori error estimates for the hp -BEM

Representation of the solution to the EFIE: $\mathbf{u} = \mathbf{u}_{\text{reg}} + \mathbf{u}_{\text{sing}}$,
 $\mathbf{u}_{\text{reg}} \in \mathbf{H}_{-}^m(\text{div}_{\Gamma}, \Gamma)$ with $m > 0$, $\mathbf{u}_{\text{sing}} = \mathbf{u}^e + \mathbf{u}^v + \mathbf{u}^{ev}$.

Application: *hp*-BEM for 3D problem of electromagnetic scattering

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Structure of singularities [Costabel, Dauge '00], [B., Heuer '10]:

$$\mathbf{u}_{\text{sing}} = \mathbf{curl}_\Gamma w + \mathbf{v}, \quad w \in H^{1/2}(\Gamma), \quad \mathbf{v} = (v_1, v_2) \in \mathbf{H}^{1/2}(\Gamma).$$

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Typical singularities:

edge singularities $\rho^{\gamma} |\log \rho|^{\beta_1}$,

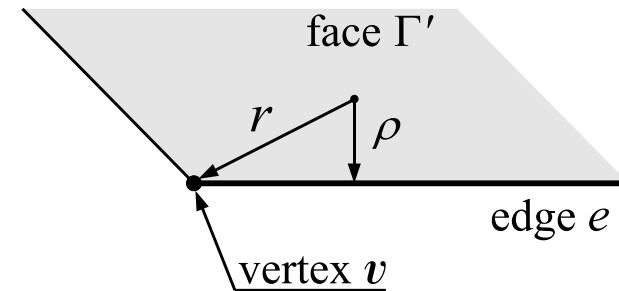
vertex singularities $r^{\lambda} |\log r|^{\beta_2}$,

edge-vertex singularities $r^{\lambda - \gamma} \rho^{\gamma} |\log r|^{\beta_3}$;

r – distance to a vertex v of Γ ,

ρ – distance to one of the edges $e \subset \Gamma$ such that $\bar{e} \ni v$;

$\gamma > \frac{1}{2}$ ($\gamma \geq \frac{1}{2}$ if Γ is an open surface), $\lambda > -\frac{1}{2}$, integers $\beta_1, \beta_2, \beta_3 \geq 0$.



Application: *hp*-BEM for 3D problem of electromagnetic scattering

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Application: hp -BEM for 3D problem of electromagnetic scattering

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Theorem 4. Let $\sigma = \min_{e,v: v \in \bar{e}} \min \{\lambda + 1/2, \gamma\}$ denote the strongest singularity.

$$\|\mathbf{u}_{\text{sing}} - \mathbf{u}_{\text{sing}}^{hp}\|_{\mathbf{X}} \preceq \begin{cases} h^\sigma p^{-2\sigma} (1 + \log(p/h))^{\tilde{\beta} + \nu} & \text{if } p \geq \sigma - \frac{1}{2}, \\ h^{p+1/2} & \text{if } 1 \leq p < \sigma - \frac{1}{2}, \end{cases}$$

$$\text{where } \tilde{\beta} := \begin{cases} \beta_3 + \frac{1}{2} & \text{if } \lambda = \gamma - \frac{1}{2}, \\ \beta_3 & \text{otherwise,} \end{cases} \quad \nu := \begin{cases} \frac{1}{2} & \text{if } p = \sigma - \frac{1}{2}, \\ 0 & \text{otherwise.} \end{cases}$$

Application: hp -BEM for 3D problem of electromagnetic scattering

Precise a priori error estimates for the hp -BEM

Rumsey's principle: find $\mathbf{u} \in \mathbf{X}$ such that $a(\mathbf{u}, \mathbf{v}) = \langle \mathbf{f}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{X}$.

Galerkin BEM: find $\mathbf{u}_N \in \mathbf{X}_N$ such that $a(\mathbf{u}_N, \mathbf{v}) = \langle \mathbf{f}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{X}_N$.

Theorem 5. Let $\sigma = \min_{e, v: v \in \bar{e}} \min \{ \lambda + 1/2, \gamma \}$ denote the strongest singularity.

Then

$$\|\mathbf{u} - \mathbf{u}_N\|_{\mathbf{X}} \preceq \begin{cases} h^\sigma p^{-2\sigma} (1 + \log(p/h))^{\tilde{\beta} + \nu} & \text{if } p \geq \sigma - \frac{1}{2}, \\ h^{p+1/2} & \text{if } 1 \leq p < \sigma - \frac{1}{2}, \end{cases}$$

where

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Conclusions

- * Optimal error estimates for $\mathbf{H}(\text{div})$ - and $\mathbf{H}(\text{curl})$ -conforming p -interpolation in two dimensions
- * Convergence of the hp -BEM for the electric field integral equation on polyhedral surfaces discretised by shape-regular meshes
- * A priori error estimation for the hp -BEM on quasi-uniform meshes; precise error estimates in terms of h , p , and the singularity exponents

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Some areas not (yet) covered

- * Non-regular (e.g., graded) meshes: convergence of the BEM
- * Exponentially convergent hp -BEM for electromagnetic problems
- * Computational aspects and implementation
- * Numerical dispersion errors
- * A posteriori error analysis for the BEM; hp -adaptive schemes
- ...

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[H\(div\)- and H\(curl\)-conforming \$p\$ -interpolation](#)

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Thank you for your attention!