

STOCHASTIC GALERKIN FINITE ELEMENT METHODS FOR SADDLE POINT PROBLEMS WITH RANDOM DATA

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Workshop “Numerical Analysis of Stochastic PDEs”
Mathematics Institute, University of Warwick
11 – 12 June, 2012

What is this talk about...

- * Saddle point problems with **random data**
- * **Stochastic Galerkin** mixed finite element method
- * Inf-sup stability of discrete problem, solution regularity, error analysis

Saddle point problems

Find $(u, p) \in V \times W$ such that

$$\begin{aligned} a(u, v) + b(v, p) &= f(v) & \forall v \in V, \\ b(u, q) &= g(q) & \forall q \in W. \end{aligned}$$

Here, V and W represent Hilbert spaces;

$a : V \times V \rightarrow \mathbf{R}$ is a symmetric bounded bilinear form,

$b : V \times W \rightarrow \mathbf{R}$ is a bounded bilinear form and

$f : V \rightarrow \mathbf{R}$ and $g : W \rightarrow \mathbf{R}$ are linear functionals.

Saddle point problems with random data

Random coefficient(s): find $(u, p) \in V \times W$ such that

$$\mathbf{a}(u, v) + b(v, p) = f(v) \quad \forall v \in V,$$

$$b(u, q) = g(q) \quad \forall q \in W.$$

Examples: groundwater flow modelling, steady state Navier-Stokes flow

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Fictitious domain approach for elliptic PDEs in random domains:
[Canuto and Kozubek '07].

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Random forces and/or boundary conditions: find $(u, p) \in V \times W$ such that

$$\begin{aligned} a(u, v) + b(v, p) &= \mathbf{f}(v) & \forall v \in V, \\ b(u, q) &= \mathbf{g}(q) & \forall q \in W. \end{aligned}$$

Example: steady flow over a step with data uncertainty

Model problem:

$$\begin{aligned} -\nu \nabla^2 \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p &= \mathbf{f} && \text{in } D, \\ \nabla \cdot \mathbf{u} &= 0 && \text{in } D, \\ \mathbf{u} &= \mathbf{g} && \text{on } \partial D_{\text{Dir}}, \\ \nu \nabla \mathbf{u} \cdot \mathbf{n} - \mathbf{n} p &= \mathbf{0} && \text{on } \partial D_{\text{Neu}}. \end{aligned}$$

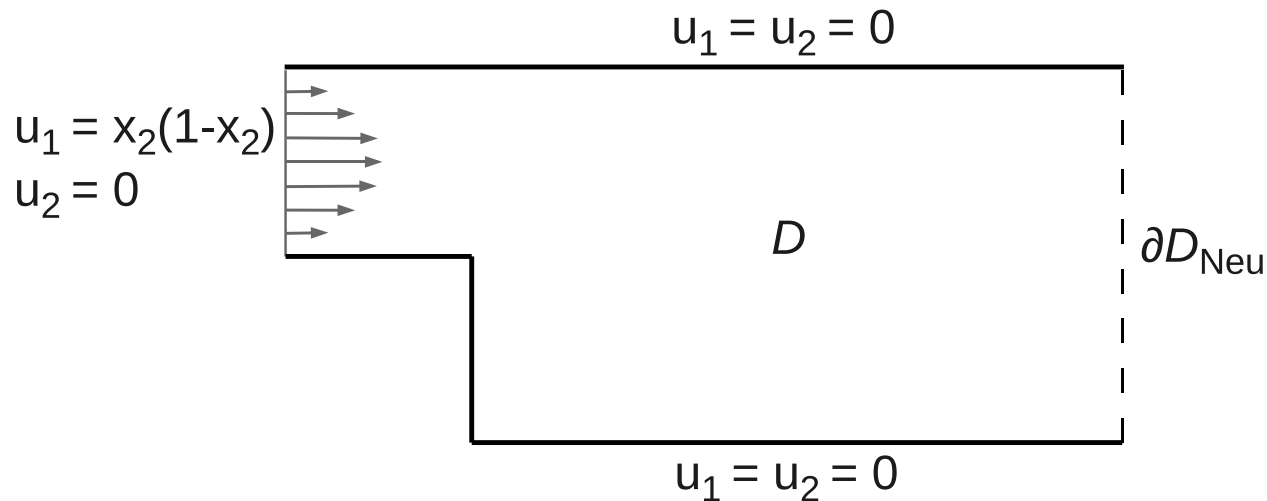


Figure 1. The backward-facing step domain.

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We can model uncertainty in the viscosity as $\nu(\omega) = \nu_0 + \nu_1 \xi_1(\omega)$.

If $\xi_1 \sim U(-\sqrt{3}, \sqrt{3})$, then ν is a **uniform random variable** with

$$\mathbb{E}[\nu(\omega)] = \nu_0, \quad \text{Var}[\nu(\omega)] = \nu_1^2.$$

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Then $\nu \sim U(\nu_{\min}, \nu_{\max})$ with $\nu_{\min} = \nu_0 - \nu_1 \sqrt{3}$, $\nu_{\max} = \nu_0 + \nu_1 \sqrt{3}$, and

$$\text{Re}(\omega) = \frac{\text{const}}{\nu(\omega)}, \quad \mathbb{E}[\text{Re}] = \text{const} \mathbb{E}[\nu^{-1}] = \frac{\text{const}^*}{\nu_1} \log \left(\frac{\nu_{\max}}{\nu_{\min}} \right).$$

Example: steady flow over a step with data uncertainty

Random viscosity: $\nu(\omega) = \nu_0 + \nu_1 \xi_1(\omega)$ with $\nu_0 = 1/50$ and $\nu_1 = 1/500$.

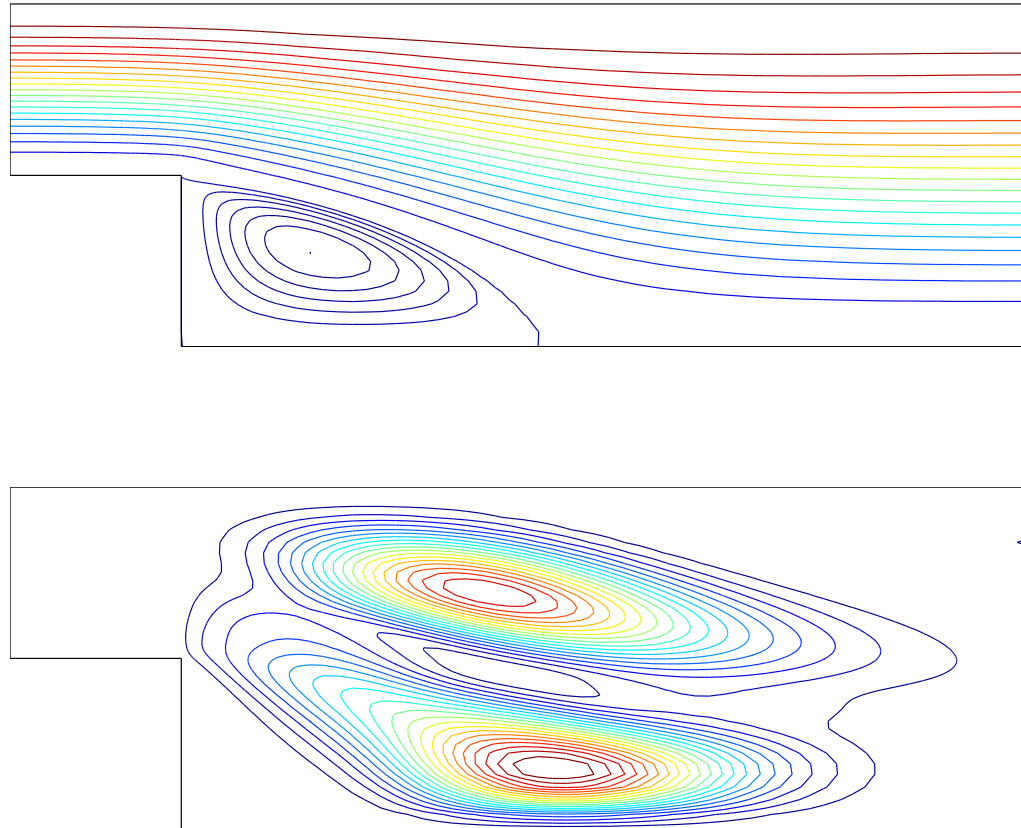


Figure 2. Streamlines of the **mean flow field** (top) and contours of the **variance of the magnitude** of flow field (bottom).

Example: steady flow over a step with data uncertainty

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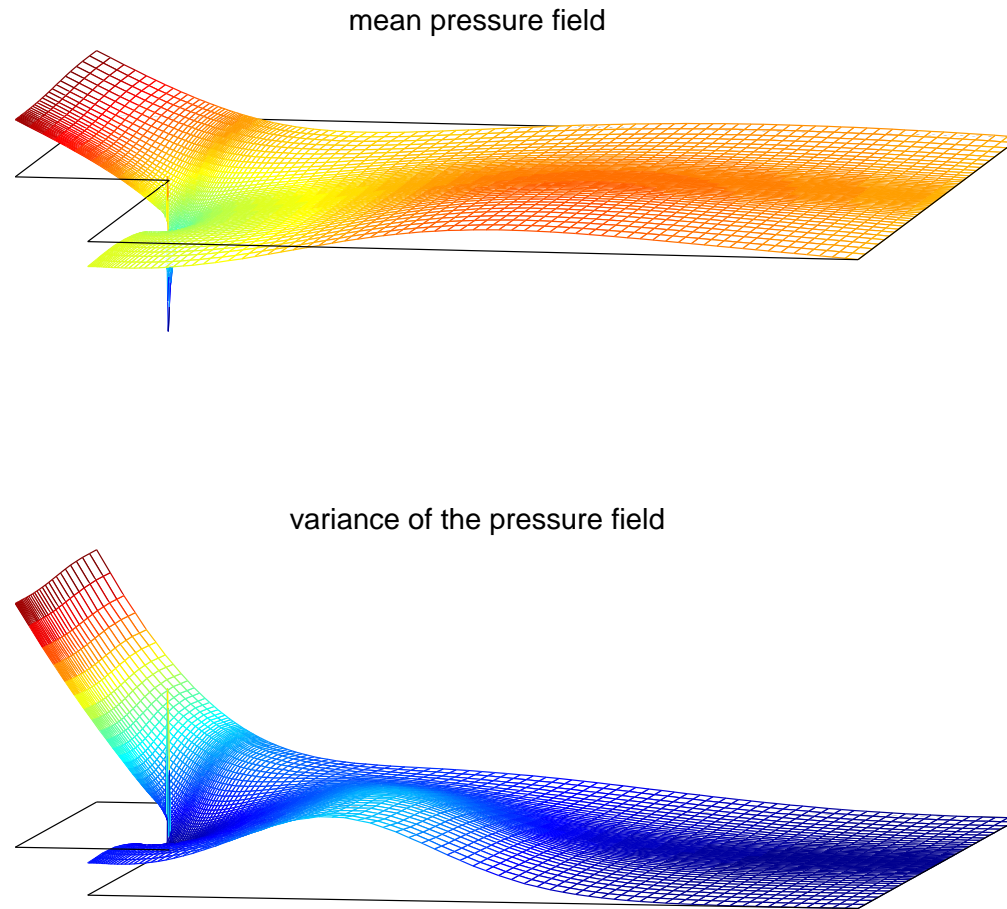


Figure 3. The mean (top) and the variance (bottom) of the pressure field.

Example: steady flow over a step with data uncertainty

More details on this problem (including stochastic Galerkin mixed finite element scheme, properties of saddle point linear systems, and analysis of preconditioning strategies):

D. Silvester, A. B. and C. Powell, A framework for the development of implicit solvers for incompressible flow problems, *Discrete and Continuous Dynamical Systems - Series S*, 2012 (to appear).

C. Powell and D. Silvester, Preconditioning steady-state Navier-Stokes equations with random data, *MIMS EPrint 2012.35*, The University of Manchester, 2012 (submitted).

Model problem

$D \subset \mathbb{R}^d$ ($d = 2, 3$) – spatial domain;

$(\Omega, \mathcal{F}, \mathbb{P})$ – complete probability space;

$A^{-1}(\mathbf{x}, \omega) : D \times \Omega \rightarrow \mathbb{R}$ – second-order correlated random field.

Model problem:

find random fields $p(\mathbf{x}, \omega)$ and $\mathbf{u}(\mathbf{x}, \omega)$ such that \mathbb{P} -almost everywhere in Ω

$$\begin{aligned} A^{-1}(\mathbf{x}, \omega) \mathbf{u}(\mathbf{x}, \omega) - \nabla p(\mathbf{x}, \omega) &= 0 & \mathbf{x} \in D, \\ \nabla \cdot \mathbf{u}(\mathbf{x}, \omega) &= 0 & \mathbf{x} \in D, \\ p(\mathbf{x}, \omega) &= g(\mathbf{x}) & \mathbf{x} \in \partial D_{\text{Dir}}, \\ \mathbf{u}(\mathbf{x}, \omega) \cdot \mathbf{n} &= 0 & \mathbf{x} \in \partial D_{\text{Neu}}. \end{aligned}$$

Useful references

- *Primal formulations, stochastic Galerkin FEM, error analysis*
[Babuška, Tempone and Zouraris '04],
[Frauenfelder, Schwab, Todor '05].
- *Stochastic collocation FEM, mixed formulation, log-normal distribution of random data*
[Ganis, Klie, Wheeler, Wildey, Yotov, and Zhang '08].
- *Stochastic Galerkin FEM, mixed formulation, linear algebra and fast solvers*
[Ernst, Powell, Silvester, and Ullmann '09],
[Elman, Furnival, and Powell '10].

Weak formulation

$X(D)$ – a Banach space of real-valued functions on D with norm $\|\cdot\|_{X(D)}$.

Vector spaces of random fields

$$L_{\mathbb{P}}^2(\Omega, X(D)) := \left\{ v(\mathbf{x}, \omega); v: D \times \Omega \rightarrow \mathbb{R}, \right. \\ \left. \|v\|_{L_{\mathbb{P}}^2(\Omega, X(D))} := \left(\mathbb{E}[\|v\|_{X(D)}^2] \right)^{1/2} < \infty \right\};$$

$$\mathcal{V} := L_{\mathbb{P}}^2(\Omega, \mathbf{H}_0(\text{div}, D)) \quad \text{and} \quad \mathcal{W} := L_{\mathbb{P}}^2(\Omega, L^2(D)).$$

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Weak formulation:

find $\mathbf{u}(\mathbf{x}, \omega) \in \mathcal{V}$ and $p(\mathbf{x}, \omega) \in \mathcal{W}$ such that

$$\begin{aligned} \mathbb{E} \left[(A^{-1}(\mathbf{x}, \omega) \mathbf{u}, \mathbf{v}) \right] + \mathbb{E} \left[(p, \nabla \cdot \mathbf{v}) \right] &= \mathbb{E} \left[(g, \mathbf{v} \cdot \mathbf{n})_{\partial D_{\text{Dir}}} \right], \\ \mathbb{E} \left[(w, \nabla \cdot \mathbf{u}) \right] &= 0 \end{aligned}$$

for all $\mathbf{v}(\mathbf{x}, \omega) \in \mathcal{V}$ and $w(\mathbf{x}, \omega) \in \mathcal{W}$.

Discretisation strategy

Discretisation method: stochastic Galerkin mixed finite elements.

Three levels of approximation

- Approximation of random data, $A^{-1}(\mathbf{x}, \omega) \approx A_M^{-1}(\mathbf{x}, \xi(\omega))$:
e.g., using the truncated Karhunen-Loève expansion of $A^{-1}(\mathbf{x}, \omega)$;
- Spatial discretisation on D :
e.g., by the lowest-order mixed FEM with mesh-size h ;
- Discretisation on $\Gamma = \xi(\Omega) \subset \mathbb{R}^M$:
e.g., global polynomial approximation of total degree $\leq k$.

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Three levels of approximation \implies three discretisation parameters (M, h, k)
and three sources of error.

Approximation of random data

$$A^{-1}(\mathbf{x}, \omega) \approx A_M^{-1}(\mathbf{x}, \omega)$$

... leads to

Perturbed weak formulation:

find $\mathbf{u}_M(\mathbf{x}, \omega) \in \mathcal{V}$ and $p_M(\mathbf{x}, \omega) \in \mathcal{W}$ such that

$$\begin{aligned} \mathbb{E} \left[(A_M^{-1}(\mathbf{x}, \omega) \mathbf{u}_M, \mathbf{v}) \right] + \mathbb{E} \left[(p_M, \nabla \cdot \mathbf{v}) \right] &= \mathbb{E} \left[(g, \mathbf{v} \cdot \mathbf{n})_{\partial D_{\text{Dir}}} \right], \\ \mathbb{E} \left[(w, \nabla \cdot \mathbf{u}_M) \right] &= 0 \end{aligned}$$

for all $\mathbf{v}(\mathbf{x}, \omega) \in \mathcal{V}$ and $w(\mathbf{x}, \omega) \in \mathcal{W}$.

Estimating the perturbation error

Lemma 1. Assume that

$$0 < A_{\min} \leq A^{-1}(\mathbf{x}, \omega) \leq A_{\max} < \infty \quad \text{a. e. in } D \times \Omega,$$

$$0 < A_{\min}^M \leq A_M^{-1}(\mathbf{x}, \omega) \leq A_{\max}^M < \infty \quad \text{a. e. in } D \times \Omega.$$

Then there exist unique solution pairs $(\mathbf{u}, p) \in \mathcal{V} \times \mathcal{W}$, $(\mathbf{u}_M, p_M) \in \mathcal{V} \times \mathcal{W}$ and

$$\|\mathbf{u} - \mathbf{u}_M\|_{\mathcal{V}} + \|p - p_M\|_{\mathcal{W}} \leq C \|A^{-1} - A_M^{-1}\|_{L^\infty(D \times \Omega)}. \quad (1)$$

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Remark 1. The constant C in (1) depends on A_{\min} , A_{\max} , A_{\min}^M , A_{\max}^M , on the inf-sup constant and the Dirichlet data...

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Remark 1. The constant C in (1) depends on A_{\min} , A_{\max} , A_{\min}^M , A_{\max}^M , on the inf-sup constant and the Dirichlet data...

...but if $\|A^{-1} - A_M^{-1}\|_{L^\infty(D \times \Omega)} \rightarrow 0$ as $M \rightarrow \infty$ (see next Lemma), then, for sufficiently large M , we can set

$$A_{\min}^M := \frac{1}{2}A_{\min}, \quad A_{\max}^M := A_{\max} + \frac{1}{2}A_{\min}.$$

Then, the constant C in (1) is independent of M .

Estimating the error in approximation of random data

Goal: upper bound for $\|A^{-1} - A_M^{-1}\|_{L^\infty(D \times \Omega)}$.

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Representation of random data using Karhunen-Loève (KL) expansion:

$$\begin{aligned} A^{-1}(\mathbf{x}, \omega) &= \mathbb{E}[A^{-1}](\mathbf{x}) + \sum_{n=1}^{\infty} \sqrt{\lambda_n} \varphi_n(\mathbf{x}) \xi_n(\omega) \\ &\approx \mathbb{E}[A^{-1}](\mathbf{x}) + \sum_{n=1}^M \sqrt{\lambda_n} \varphi_n(\mathbf{x}) \xi_n(\omega) =: A_M^{-1}(\mathbf{x}, \omega). \end{aligned}$$

Lemma 2 [Frauenfelder, Schwab, Todor '05]. Assume:

- (i) $\{\xi_n\}_{n=1}^{\infty}$ is uniformly bounded;
- (ii) covariance function $C[A^{-1}](\mathbf{x}, \mathbf{x}')$ is (piecewise) analytic on $D \times D$. Then

$$\|A^{-1} - A_M^{-1}\|_{L^\infty(D \times \Omega)} \leq C e^{-cM^{1/d}}.$$

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$$\|A^{-1} - A_M^{-1}\|_{L^\infty(D \times \Omega)} \leq C e^{-cM^{1/d}}.$$

Lemma 1 + Lemma 2 \implies

Theorem 1. $\|\mathbf{u} - \mathbf{u}_M\|_{\mathcal{V}} + \|p - p_M\|_{\mathcal{W}} = \mathcal{O}\left(e^{-cM^{1/d}}\right)$.

More assumptions ...

We further assume that

- random variables $\xi_n : \Omega \rightarrow \mathbb{R}$ ($n = 1, 2, \dots$) are independent;
- images $\Gamma_n = \xi_n(\Omega)$ are bounded intervals in \mathbb{R} ;
- $\exists \rho_n : \Gamma_n \rightarrow \mathbb{R}^+$ – a density function of ξ_n ($n = 1, \dots, M$);

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... then

- $\mathbf{u}_M(\mathbf{x}, \omega) = \mathbf{u}_M(\mathbf{x}, \xi_1(\omega), \dots, \xi_M(\omega))$,
 $p_M(\mathbf{x}, \omega) = p_M(\mathbf{x}, \xi_1(\omega), \dots, \xi_M(\omega))$;

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 $p_M(\mathbf{x}, \omega) = p_M(\mathbf{x}, \xi_1(\omega), \dots, \xi_M(\omega))$;
- $\rho(\mathbf{y}) := \prod_{n=1}^M \rho_n$ – the joint probability density of (ξ_1, \dots, ξ_M) , where
 $\mathbf{y} = (\mathbf{y}_1, \dots, \mathbf{y}_M) \in \Gamma$ with $\mathbf{y}_n = \xi_n(\omega)$ ($n = 1, \dots, M$), and
 $\Gamma = \text{supp } \rho = \Gamma_1 \times \dots \times \Gamma_M \subset \mathbb{R}^M$;

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- $(\Omega, \mathcal{F}, \mathbb{P})$ can be replaced by $(\Gamma, \mathcal{B}(\Gamma), \rho(\mathbf{y})d\mathbf{y})$;
- for any measurable $\varphi = \varphi(\xi_1, \dots, \xi_M)$, one has $\mathbb{E}[\varphi] = \int_{\Gamma} \varphi(\mathbf{y}) \rho(\mathbf{y})d\mathbf{y}$.

... and another weak formulation

Denote

$$\mathbf{V} := L^2_\rho(\Gamma, \mathbf{H}_0(\text{div}; D)), \quad W := L^2_\rho(\Gamma, L^2(D));$$

$$a_M(\mathbf{u}, \mathbf{v}) = (A_M^{-1} \mathbf{u}, \mathbf{v}), \quad b(p, \mathbf{v}) = (p, \nabla \cdot \mathbf{v}); \quad \ell(\mathbf{v}) = (g, \mathbf{v} \cdot \mathbf{n})_{\partial D_{\text{Dir}}}.$$

Parametric deterministic formulation:

find $\mathbf{u}_M(\mathbf{x}, \mathbf{y}) \in \mathbf{V}$ and $p_M(\mathbf{x}, \mathbf{y}) \in W$ such that

$$\begin{aligned} \mathbb{E} [a_M(\mathbf{u}_M, \mathbf{v})] + \mathbb{E} [b(p_M, \mathbf{v})] &= \mathbb{E} [\ell(\mathbf{v})], \\ \mathbb{E} [b(w, \mathbf{u}_M)] &= 0 \end{aligned}$$

for all $\mathbf{v}(\mathbf{x}, \mathbf{y}) \in \mathbf{V}$ and $w(\mathbf{x}, \mathbf{y}) \in W$.

Remark 2. This problem is uniquely solvable under the assumptions in the statement of Lemma 1.

Stochastic Galerkin mixed FEM

Discrete subspaces

(i) on the spatial domain $D \subset \mathbb{R}^d$: $\mathbf{X}_h^{\text{div}} \subset \mathbf{H}_0(\text{div}; D)$, $X_h^0 \subset L^2(D)$;

(ii) on the outcomes set $\Gamma \subset \mathbb{R}^M$: $S_k \subset L^2_\rho(\Gamma)$.

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Discrete formulation (sGFEM):

find $\mathbf{u}_{hk}(\mathbf{x}, \mathbf{y}) \in \mathbf{X}_h^{\text{div}} \otimes S_k$ and $p_{hk}(\mathbf{x}, \mathbf{y}) \in X_h^0 \otimes S_k$ satisfying

$$\mathbb{E} [a_M(\mathbf{u}_{hk}, \mathbf{v})] + \mathbb{E} [b(p_{hk}, \mathbf{v})] = \mathbb{E} [\ell(\mathbf{v})],$$

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for all $\mathbf{v} \in \mathbf{X}_h^{\text{div}} \otimes S_k$ and $w \in X_h^0 \otimes S_k$.

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for all $\mathbf{v} \in \mathbf{X}_h^{\text{div}} \otimes S_k$ and $w \in X_h^0 \otimes S_k$.

Theorem 2. Let $\mathbf{X}_h^{\text{div}}$, X_h^0 be a deterministic **inf-sup stable** pairing with discrete inf-sup constant β . Then, for any choice of $S_k \subset L^2_\rho(\Gamma)$, the pairing $(\mathbf{X}_h^{\text{div}} \otimes S_k)$, $(X_h^0 \otimes S_k)$ for the sGFEM is **inf-sup stable** with the same discrete inf-sup constant β , and the sGFEM converges quasi-optimally.

Estimating the stochastic Galerkin error

Total error of the stochastic Galerkin FEM:

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$$E_{hk} := \|\mathbf{u}_M - \mathbf{u}_{hk}\|_{\mathbf{V}} + \|p_M - p_{hk}\|_W.$$

Decomposition of the error

$$\begin{aligned} E_{hk} &\preceq \inf_{\mathbf{v} \in \mathbf{X}_h^{\text{div}} \otimes S_k} \|\mathbf{u}_M - \mathbf{v}\|_{\mathbf{V}} + \inf_{w \in X_h^0 \otimes S_k} \|p_M - w\|_W \\ &\preceq \|\mathbf{u}_M - \Pi_h^{\text{div}} \mathbf{u}_M\|_{\mathbf{V}} + \|p_M - \Pi_h^0 p_M\|_W \\ &\quad + \|\mathbf{u}_M - \Pi_k^{0,\rho} \mathbf{u}_M\|_{\mathbf{V}} + \|p_M - \Pi_k^{0,\rho} p_M\|_W \\ &= \{ \text{'spatial' } h\text{-error} \} + \{ \text{'stochastic' } k\text{-error} \}, \end{aligned}$$

Π_h^{div} is an $\mathbf{H}(\text{div}; D)$ -conforming interpolation operator (defined elementwise),

Π_h^0 is $L^2(D)$ -projector onto $X_h^0 \subset L^2(D)$,

$\Pi_k^{0,\rho}$ is $L_\rho^2(\Gamma)$ -orthogonal projection onto $S_k \subset L_\rho^2(\Gamma)$.

Regularity of the solution

Parameterised coefficient:

$$A_M^{-1}(\mathbf{x}, \mathbf{y}) = \mathbb{E}[A^{-1}](\mathbf{x}) + \sum_{n=1}^M \sqrt{\lambda_n} \varphi_n(\mathbf{x}) y_n.$$

Spatial regularity

If $\mathbb{E}[A^{-1}] \in C^1(\bar{D})$ and $C[A^{-1}]$ is smooth on $D \times D$, then $\exists r > 0$ such that

$$(\mathbf{u}_M, p_M) \in L^2_\rho(\Gamma; \mathbf{H}^r(\text{div}, D)) \times L^2_\rho(\Gamma; H^r(D)).$$

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Regularity with respect to y_1, \dots, y_M

Lemma 4. If Γ_n ($n \in \{1, 2, \dots, M\}$) is a bounded interval in \mathbb{R} then the functions \mathbf{u}_M and p_M , as functions of variable y_n , can be analytically extended to **the same region** of the complex plane:

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Lemma 4. If Γ_n ($n \in \{1, 2, \dots, M\}$) is a bounded interval in \mathbb{R} then the functions \mathbf{u}_M and p_M , as functions of variable y_n , can be analytically extended to **the same region** of the complex plane:

$$\Sigma_n := \left\{ z \in \mathbb{C}; |z - y_n^0| < \frac{\inf_{\mathbf{x} \in D} (A_M^{-1}(\mathbf{x}, y_n^0, \mathbf{y}_n^*))}{\sqrt{\lambda_n} \|\varphi_n\|_{L^\infty(D)}} \quad \forall y_n^0 \in \Gamma_j \right\},$$

where $\mathbf{y}_n^* = (y_1, \dots, y_{n-1}, y_{n+1}, \dots, y_M)$ for any $n \in \{1, 2, \dots, M\}$.

Estimating the stochastic Galerkin error

Theorem 3. Assume:

- (i) KL-expansion of A^{-1} with **uniformly distributed** random variables ξ_n ;
- (ii) given $\mathbf{k} = (k_1, \dots, k_M) \in \mathbb{N}_0^M$, $S_{\mathbf{k}} := S_{k_1}(\Gamma_1) \otimes \dots \otimes S_{k_M}(\Gamma_M)$;
- (iii) technical coercivity assumption. Then there holds

$$\|\mathbf{u}_M - \mathbf{u}_{hk}\|_{\mathbf{V}} + \|p_M - p_{hk}\|_W \leq C \left(h^{\min\{r,1\}} + \sum_{n=1}^M \eta_n^{k_n+1} \right),$$

where $\eta_n = \left(\chi_n + \sqrt{\chi_n^2 - 1} \right)^{-1} \in (0, 1)$ with $\chi_n = 1 + \frac{\text{const}}{\sqrt{\lambda_n} \|\varphi_n\|_{L^\infty(D)}}$
for $n = 1, \dots, M$.

References

More details of this work:

A. B., C. Powell and D. Silvester, A priori error analysis of stochastic Galerkin mixed approximations of elliptic PDEs with random data, *SIAM J. Numer. Anal.*, 2012 (to appear).

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Thank you for your attention!